

Context-Aware Network Stack Optimization

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Outline

- 1 Context and Objectives
- 2 Motivating Examples
- 3 Target Architecture
 - Constraint-based Decision Algorithm
 - Current Status
- 4 Conclusion and Short-term Plans

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Context and Objectives

Heterogeneous environment but some unifying blocks

- Vehicular networks
 - Rapidly changing conditions
 - Mobility geographical and time patterns
- Ad-hoc environment
 - Few or no structural organisation
 - Possibility of insider attacks
- Network mobility and Multihoming
 - Several interfaces, networks and routes available at once to choose from
 - ISO CALM mandates IPv6 use

Context and Objectives

No repository of complete information without cross-layering

- Network information and control scattered between layers
 - All parameters contribute to the overall performance
 - No full read/write access to all of them
- Consideration of cross-layer approaches
 - Share information between layer implementations
 - Each layer makes its own optimizing decision
- Usual issues of such designs
 - Linked layers too specialized for the considered environment
 - Unintended interactions with each other or other parts of the system
- Out-of-stack cross-layers information busses
 - MobileMAN, ULLA, CALM Manager,...
 - Doesn't quite solve the bad interaction problem

Context and Objectives

Use the network resources as soon as possible and as much as supported

- Fully informed decision out of the stack
 - Based on all available information
 - Updates parameters of several layers at once
- Advantages:
 - Avoid over-specialization of layers
 - Work around bad interactions
 - Can use non network-related information
 - History, context, localization, . . .

⇒ Replace a knowledgeable user tweaking their parameters

- knows the full current network performance
- has an idea of the current best achievable
- knows reasonably well what is soon to change
- can change any parameter

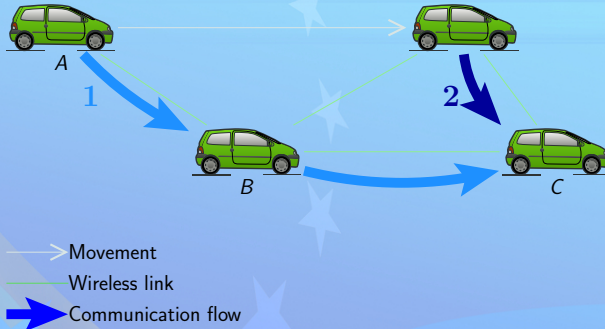
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Motivating Examples

Transport adaptation on link characteristics change

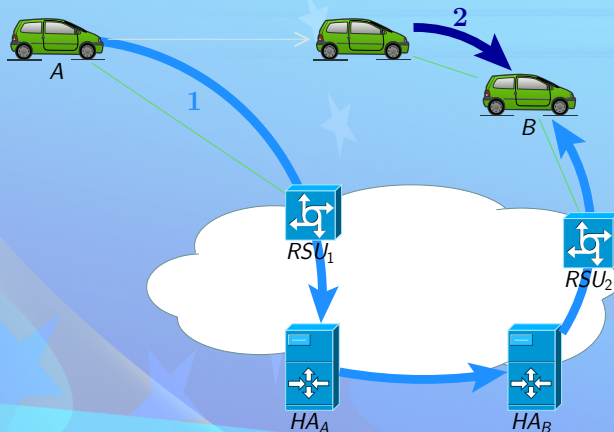
- Several possible changes in routes configuration
 - increase or reduction in the number of hops in a mesh network



Motivating Examples

Transport adaptation on link characteristics change

- Several possible changes in routes configuration
 - increase or reduction in the number of hops in a mesh network
 - switch from NEMO routes to MANET routes (or opposite)



Motivating Examples

Transport adaptation on link characteristics change

- Several possible changes in routes configuration
 - increase or reduction in the number of hops in a mesh network
 - switch from NEMO routes to MANET routes (or opposite)
- Ever-varying link parameters
 - multipath fading
 - interferences

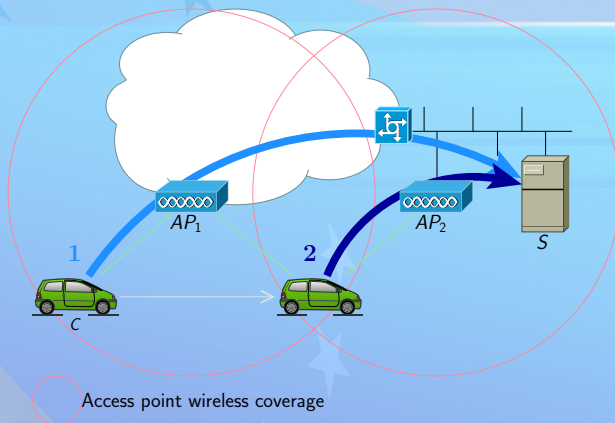
Motivating Examples

Transport adaptation on link characteristics change

- Several possible changes in routes configuration
 - increase or reduction in the number of hops in a mesh network
 - switch from NEMO routes to MANET routes (or opposite)
- Ever-varying link parameters
- Transport protocol not directly aware of such changes
 - Slow feedback-based adaptation to new link and path characteristics
 - Need information about the link and path performances
 - Similar issues for a new connection: expected path throughput as observed on other sockets along the same path
- Application parameters adjustment
 - quality
 - sampling rate

Motivating Examples

Transport adaptation on link characteristics change

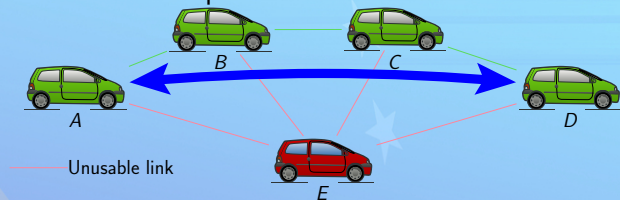


- Choose the most appropriate uplink or route
 - Based on current measurements
 - Based on previous observations
- Inform transport/application as previously mentioned

Motivating Examples

Rogue VANET Node

- *E* advertises its presence but doesn't forward traffic properly



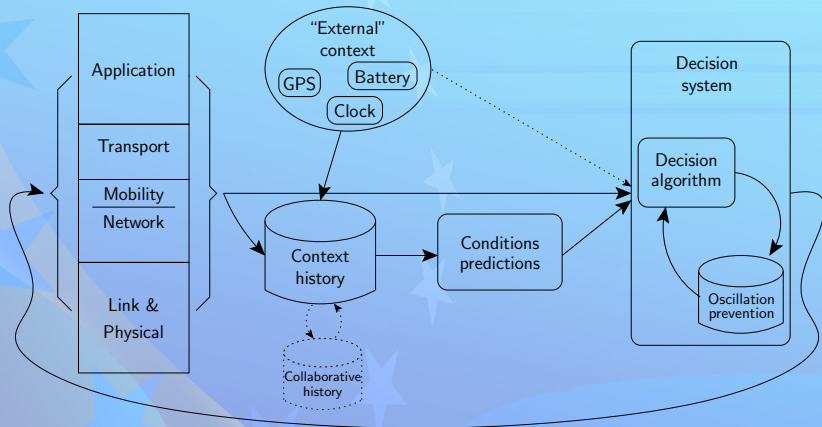
- Communication between *A* and *D* not possible along the shortest path
- Switching to another route desirable
- Quick upper layers adjustment needed afterwards

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Target Architecture

Towards a global optimization system



Target Architecture

Combining observation, prediction and decision

- Abstracted metrics from the stack
 - datarate, delay, ETX, RTT, loss, ...
- Context observations and history
 - human timescale: days or weeks
 - predict forthcoming conditions based on previous observations in similar contexts (day of the week, localization, movement pattern)
- Decision engine

internal history to avoid short-period oscillations

hints to the stack to finally optimize the network usage

Target Architecture

Optimization decision based on global knowledge

- Globally aggregated information from the stack layers
 - Application: $I_{\text{app}}(s, t) = \{c = \text{codec}(t), \dots\}$
 - Transport: $I_{\text{trp}}(s, t) = \{thr = \text{throughput}(s, t), \text{rtt}(s, t), \dots\}$
 - Network: $I_{\text{rt}}(t) = \{nh_B = \text{nextHop}(B, t), \dots\}$
- Relative impact of the combination on current performance
 - “For socket s , a throughput of thr , needed by codec c , is achievable towards node B along a path starting with nh_B .”
 - Identification of other communications with common characteristics (e.g. same destination) but different performance (e.g. higher throughput)
- Hint the network stack layer to adapt to the possible conditions e.g.,
 - change interface modulation or power
 - switch route for an address (or range), perform a handover
 - update transport state parameters
 - modify application parameters (e.g. encoding or rate)

Constraint-based Decision Algorithm

Motivation and basic idea

- Large configuration space → Combinatorial search techniques
- Modelled as a **Constraint Programming** problem
- The constraints solver unifies parameters to derives hints for the stack
 - Application quality:
 $Qual(Quality, Throughput, Jitter, RTT, PER)$
 - Application socket: $SocketDestination(Socket, Destination)$
 - Transport and routing conditions:
 $Routing(Destination, Route, Interface, Throughput, Jitter, RTT, PER)$
- Variables to unify are
 - observed conditions on the links/networks/paths (offer)
 - possible configurations of the layers (demand)

Constraint-based Decision Algorithm

Example relations for a simplified model

Observed network performances

Destination	Route	Interface	Throughput	Jitter	RTT	PER
Addr1	NH2	eth0	2 Mbps	1×10^{-4} s	10×10^{-3} s	0%
Addr1	NH1	wlan0	900 kbps	1×10^{-3} s	100×10^{-3} s	10%
Addr2	NH1	wlan0	450 kbps	1×10^{-3} s	250×10^{-3} s	30%
...						

Socket between applications and destinations

Socket	Application	Destination
1	App1	Addr1
...		

Interface costs (switching + usage)

Interface	Cost
eth0	10
wlan0	100
ppp0	250
...	

Application App1 parameters and requirements

Quality	Throughput	Jitter	RTT	PER
1	≥ 1.5 Mbps	$\leq 10^{-3}$	$\leq 10 \times 10^{-4}$ s	$\leq 10 \times 10^{-3}$
2	≥ 1 Mbps	idem	idem	idem
3	≥ 500 kbps	$\leq 10^{-2}$	$\leq 10 \times 10^{-3}$ s	idem

Constraint-based Decision Algorithm

Optimizing a cost function

- Parameter valuation trying to minimize a cost function e.g.

$$\min (\alpha \cdot rtt - \beta \cdot thr + \gamma \cdot C_{if})$$

- minimize *rtt*
- maximize *throughput*
- minimize interface cost

Current Status

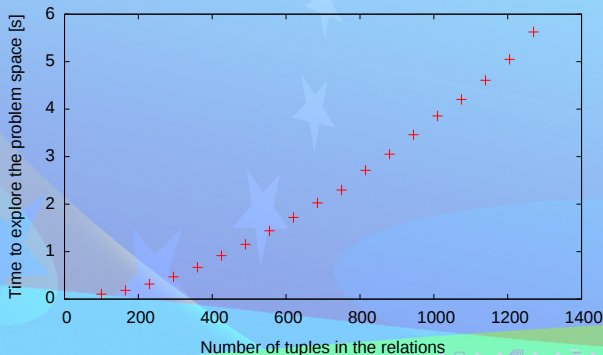
Core components under development

- Python/Netlink implementation under Linux
 - NETLINK_ROUTE, pushed by the kernel
 - link configuration parameters (RTMGRP_LINK)
 - neighbor information (RTMGRP_NEIGH)
 - interface addresses (RTMGRP_IPV6_IFADDR)
 - route information (RTMGRP_IPV6_ROUTE)
 - NETLINK_INET_DIAG, upon request
 - socket information
 - transport parameters
 - not widely available (yet)
 - passing hints back to the stack to change parameters
- MiniZinc Constraint Solver
 - current model similar to previously outlined
 - extended by history and cost relations
 - subject to change

Current Status

Timing evaluation of the solver

- CSP model randomly generated (max 5 interfaces, 190 destinations, 95 sockets)
- Coherent data (respecting ranges and correlations of parameters)
- 100 runs on an Intel Core2 Duo 2 GHz, 1 GB RAM
- All optimizations disabled → raw estimate of a higher bound



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Conclusion and Short-term Plans

- Global cross-layer optimization framework
 - External decision process
- Early implementation blocks
- Ongoing work
 - Finish the prototype implementation
 - Generalize the use of Netlink to adjust parameters
 - Unification of data
- Next steps
 - Acquire network and contextual data samples
 - Large scale simulations
 - Consider other decision systems

Thanks

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Backup

Metrics, statuses and parameters

Metrics, statuses and parameters

- Raw characteristics rate, status, bytes, lost segments (RR), lost fragments (FER), link, noise (RSSI, SNIR) ;
- Notifications: link_up, link_down, link_quality_changed [ULL], transmission power
 - for each MAC neighbour (e.g. AP/Cell Tower in infrastructure mode; all neighbours for ad-hoc modes)

Contextual information VLAN [802.1q], SSID [802.11],
CellID,...

- Network/Mobility
- Transport
- Application
- See also [RFC4907]

Target Architecture

Metrics, statuses and parameters

- Physical/Link
- Network/Mobility
 - abstract route metrics
 - MTUs
 - possible next hops to an address/range,
 - route addition/removal/change
 - ARP/NDP: mapping from next hop to MAC address
 - single-interface handoff decisions
- Transport
- Application
- See also [RFC4907]

◀ Architecture description

Target Architecture

Metrics, statuses and parameters

- Physical/Link
- Network/Mobility
- Transport
 - throughput (for TCP: cwnd, ssthresh, wnd)
 - RTT
 - loss rate
 - congestion information about paths
 - path MSS
 - peers' network address(es)
- Application
- See also [RFC4907]

◀ Architecture description

Target Architecture

Metrics, statuses and parameters

- Physical/Link
- Network/Mobility
- Transport
- Application
 - requirements in end-to-end bandwidth
 - end-to-end delay limits
 - need for packet reliability (implicitly stated when choosing the transport)
 - configurable modes of operation (e.g. codecs), and all of the above for each
 - “satisfaction” (completely ad-hoc to the application e.g., peer feedback on validity of data)
- See also [RFC4907]